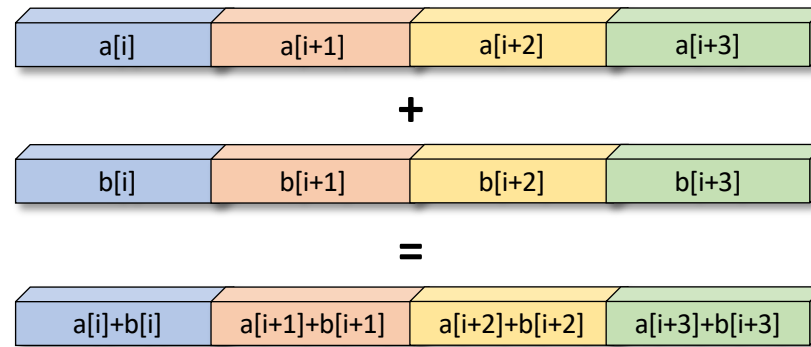


# What Every Computational Physicist Should Know About Computer Architecture\*



\*Plus some other useful technology

Ian Cosden, Princeton University

Steve Lantz, Cornell University



# Outline

- Motivation
- HPC Cluster
- Compute
- Memory
- Disk
- Other Architectures

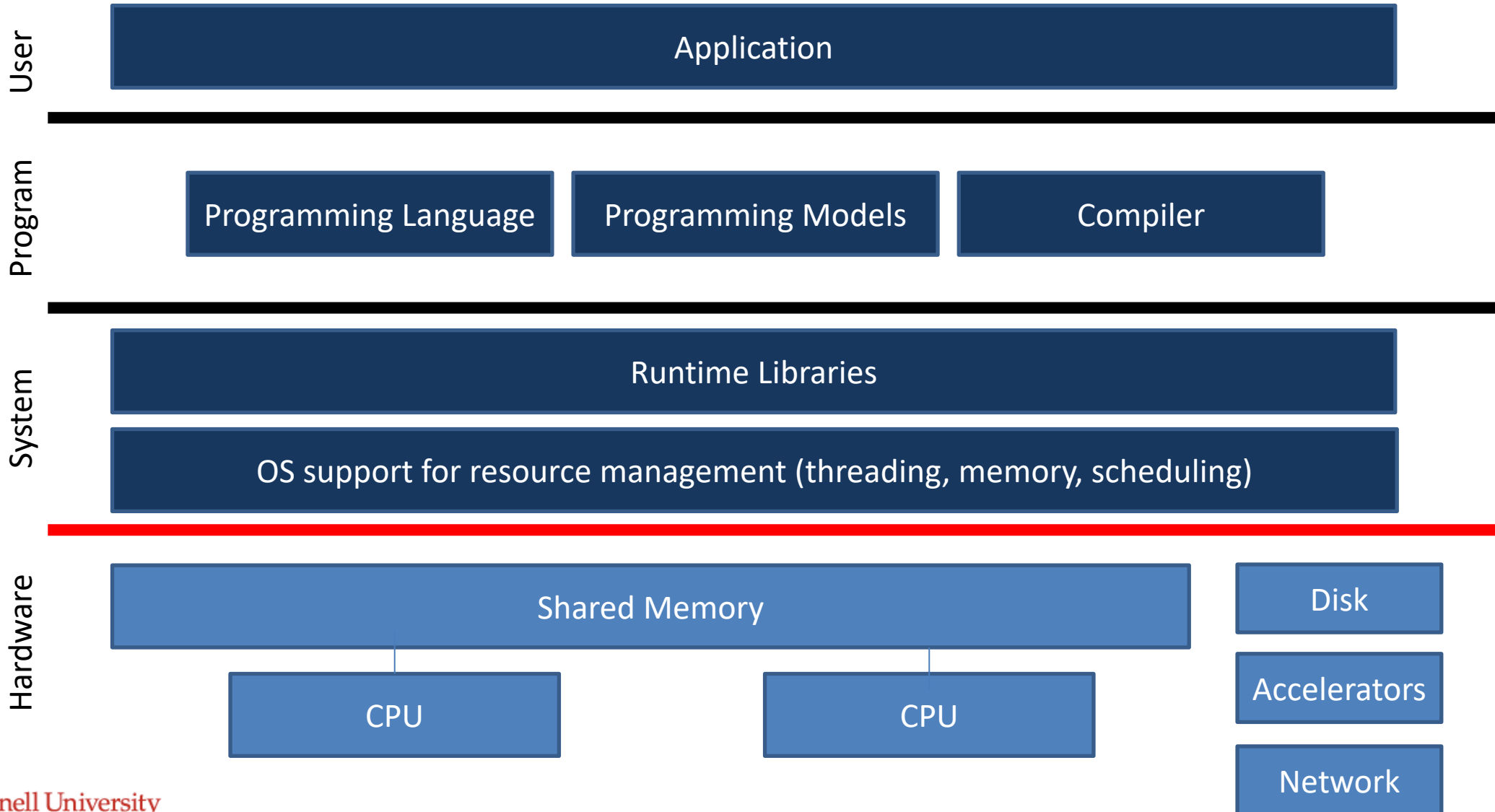


# Why Care About the Hardware?

- Get the most out of this week
- Be able to ask better questions and understand the answers
- Architecture changes can force new design and implementation strategies
  - Prevent programming mistakes
  - Make educated decisions
- Exploit the hardware to your advantage (performance)

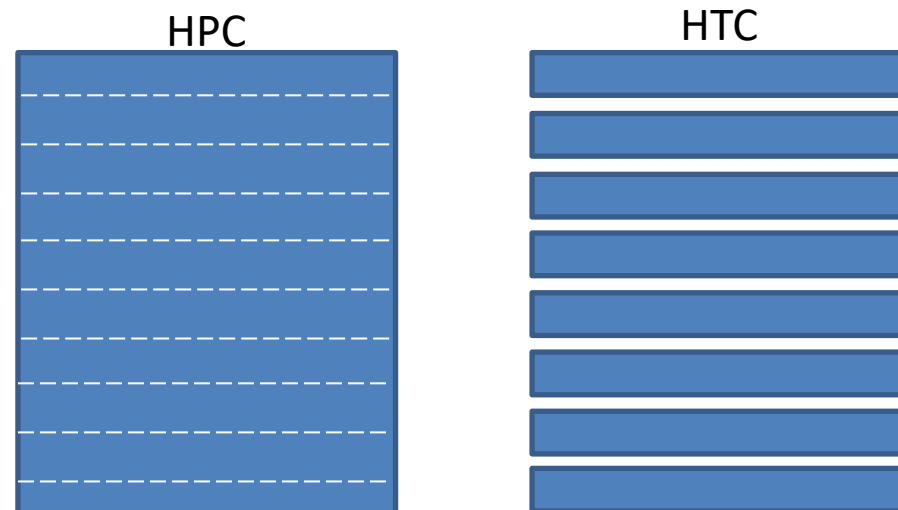


# Hardware is the Foundation



# Why Care About HPC Hardware?

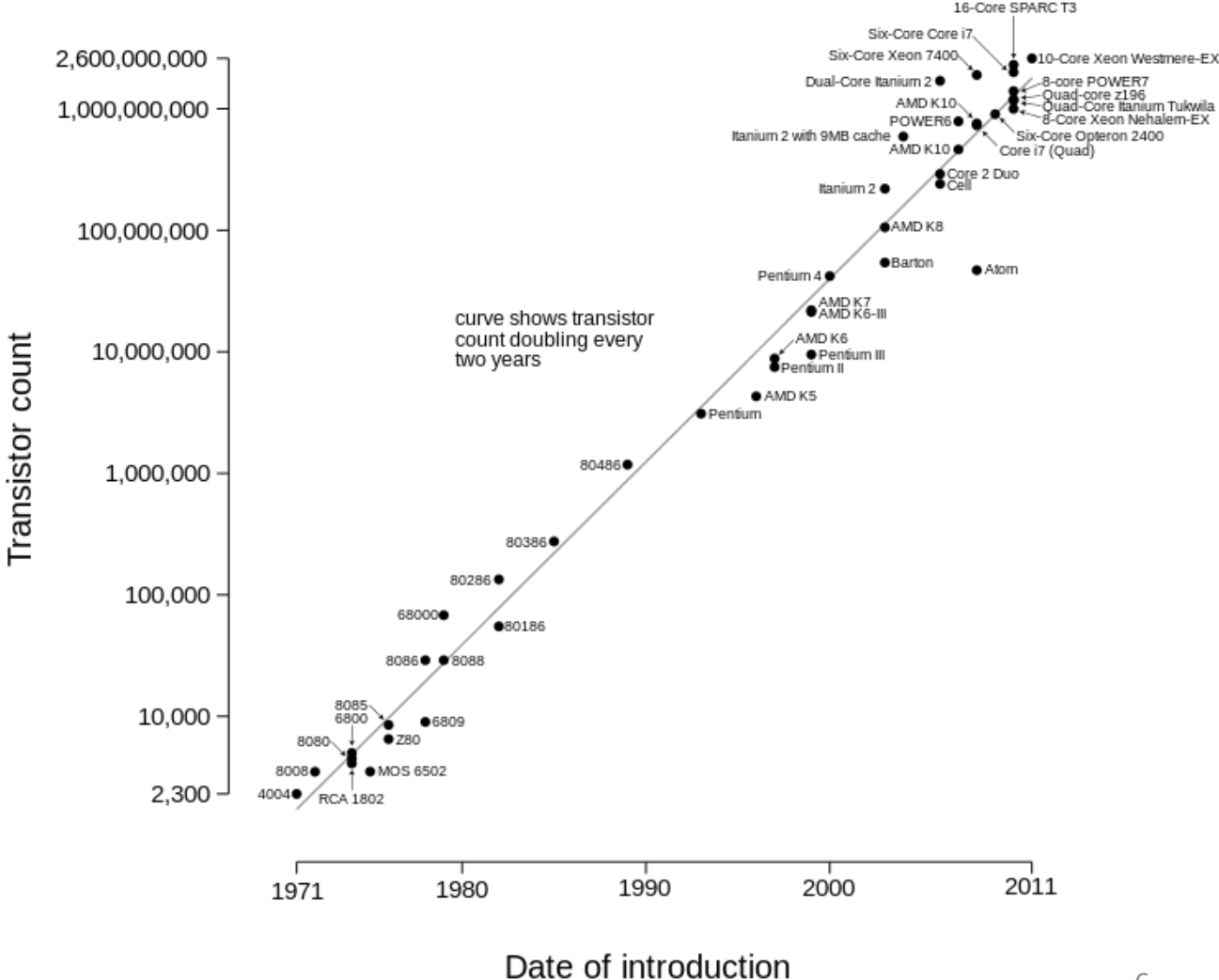
- High-Performance Computing (HPC)
  - Aggregate computing power in order to deliver far more capacity than a single computer
  - Supercomputers
- Some problems demand it from the onset; many problems evolve to need it
  - When you outgrow your laptop, desktop, departmental server
  - Ask: do you need greater *capability*, or just *capacity*?
  - Either way, HPC clusters run lots of High-Throughput Computing (HTC) jobs



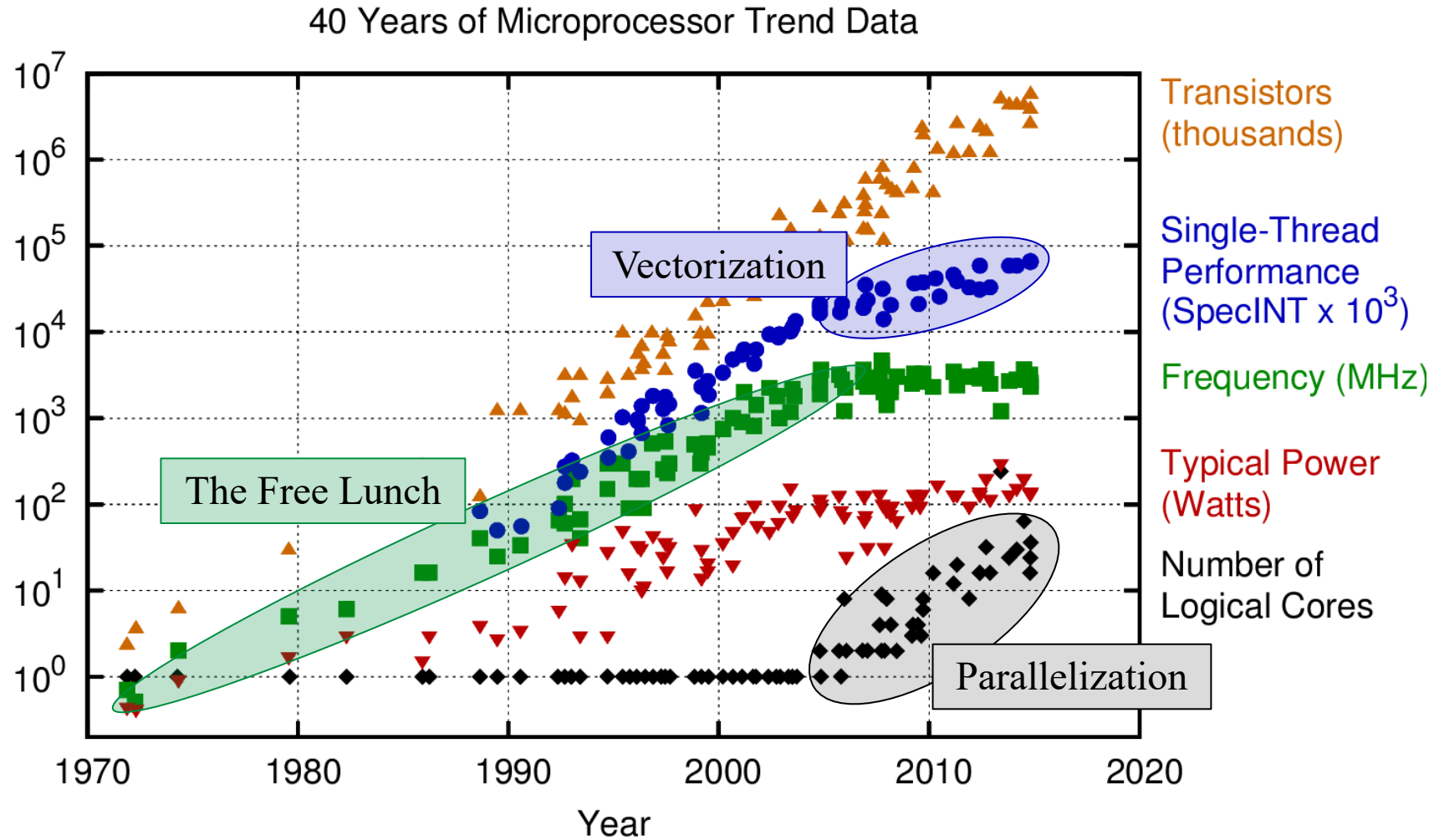
# Moore's Law

- Number of transistors doubles ever 18-24 months
- More transistors = better, right?

Microprocessor Transistor Counts 1971-2011 & Moore's Law



# The Free Lunch is Over



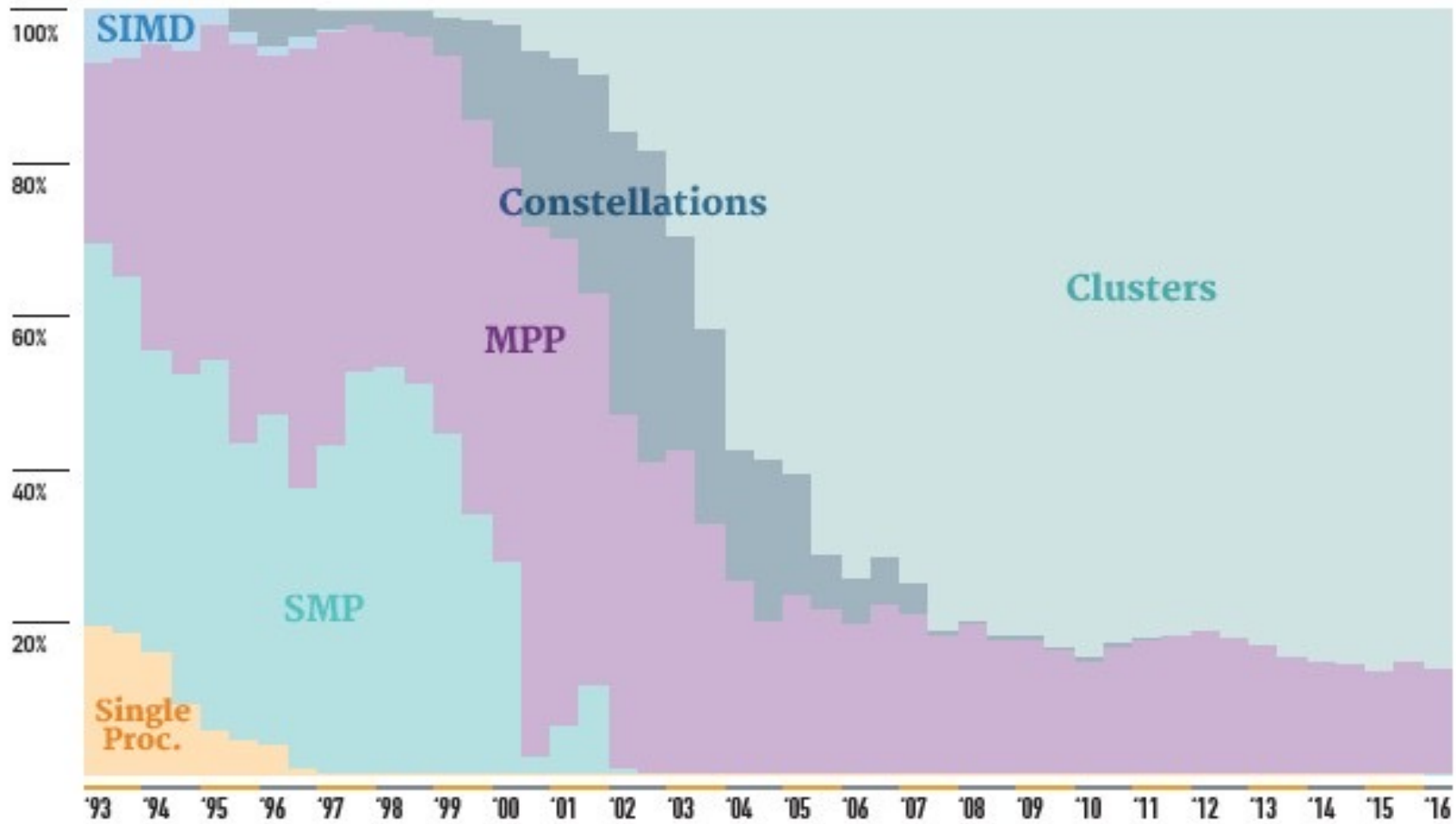
Original data up to the year 2010 collected and plotted by M. Horowitz, F. Labonte, O. Shacham, K. Olukotun, L. Hammond, and C. Batten  
New plot and data collected for 2010-2015 by K. Rupp

<https://www.karlrupp.net/2015/06/40-years-of-microprocessor-trend-data/>



# Top 500 Supercomputers

<https://www.top500.org>

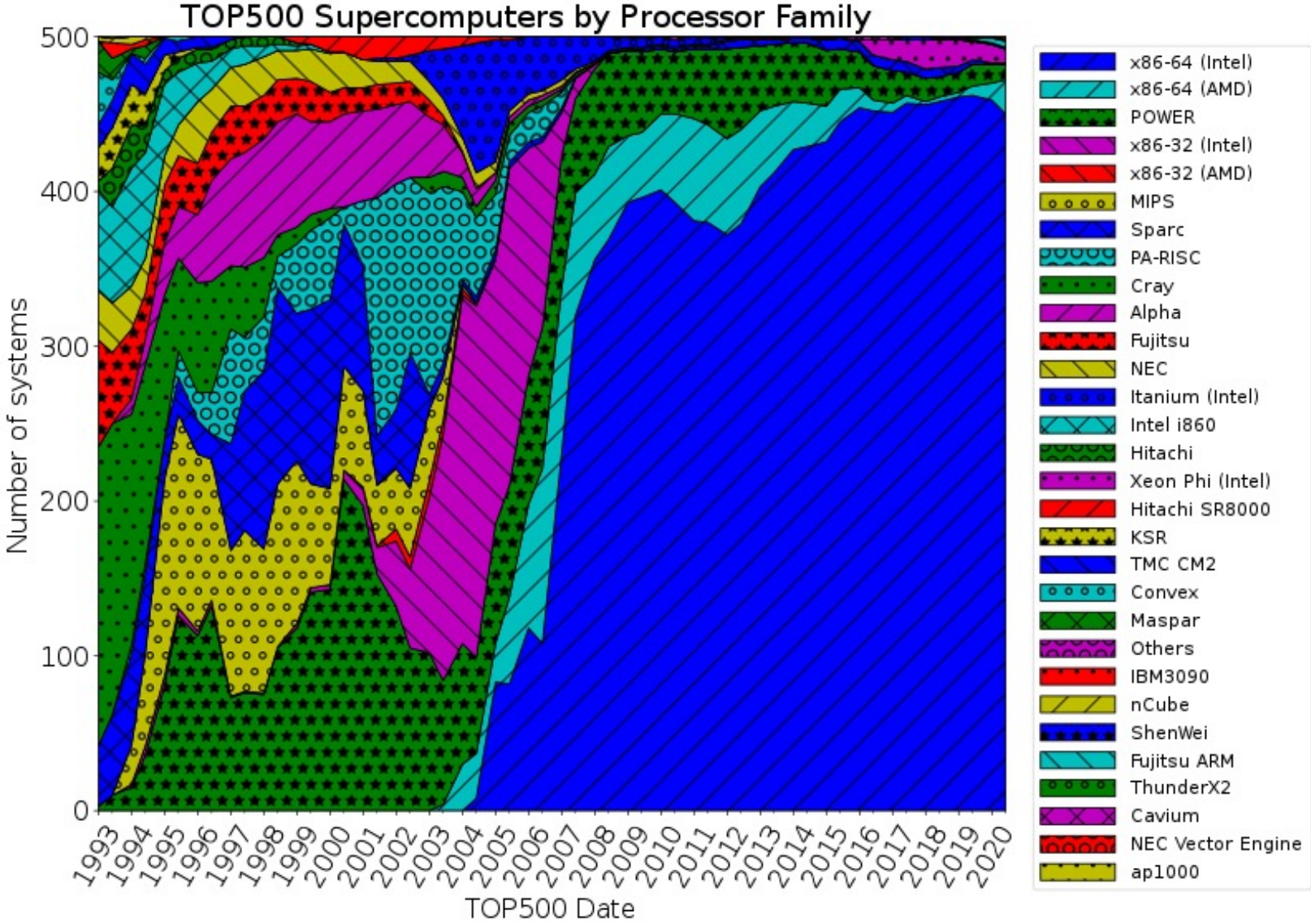


<https://www.nextplatform.com/2016/06/20/china-topples-united-states-top-supercomputer-user/>





# Why Talk About Intel Architecture?



# Outline

- Motivation
- HPC Cluster
- Compute
- Memory
- Disk
- Other Architectures



# Zoom In On A Cluster

- A cluster is just *connected* collection of computers called nodes
- The high-speed network that connects the cluster is called the interconnect
- A single, unconnected node is usually just called a server
- Entire clusters, as well as stand-alone servers, are sometimes referred to as machines



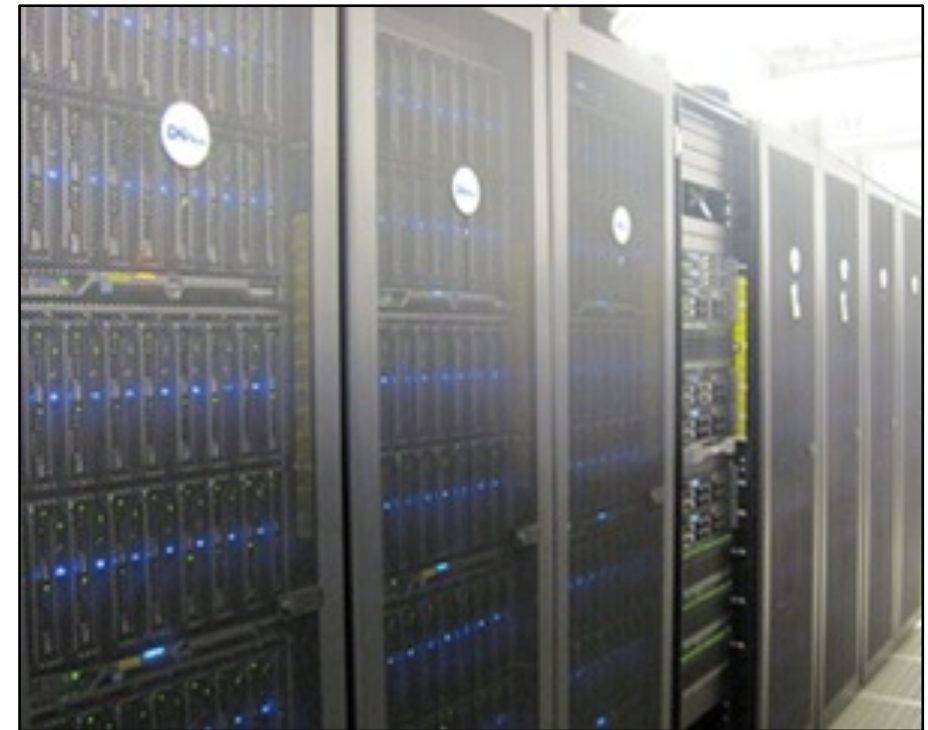
# Parallel Computers

## HPC Cluster: the vast majority of HPC systems

- A collection of servers connected to form a single entity
  - Each is essentially a self-contained computer
  - OS with CPU, RAM, hard drive, etc.
- Stored in racks in a dedicated machine room
- Networked together a via low-latency interconnect
  - Ethernet < InfiniBand, Omni-Path (Intel)
- Interconnect extends to shared storage

## SMP System: Symmetric Multi-Processing

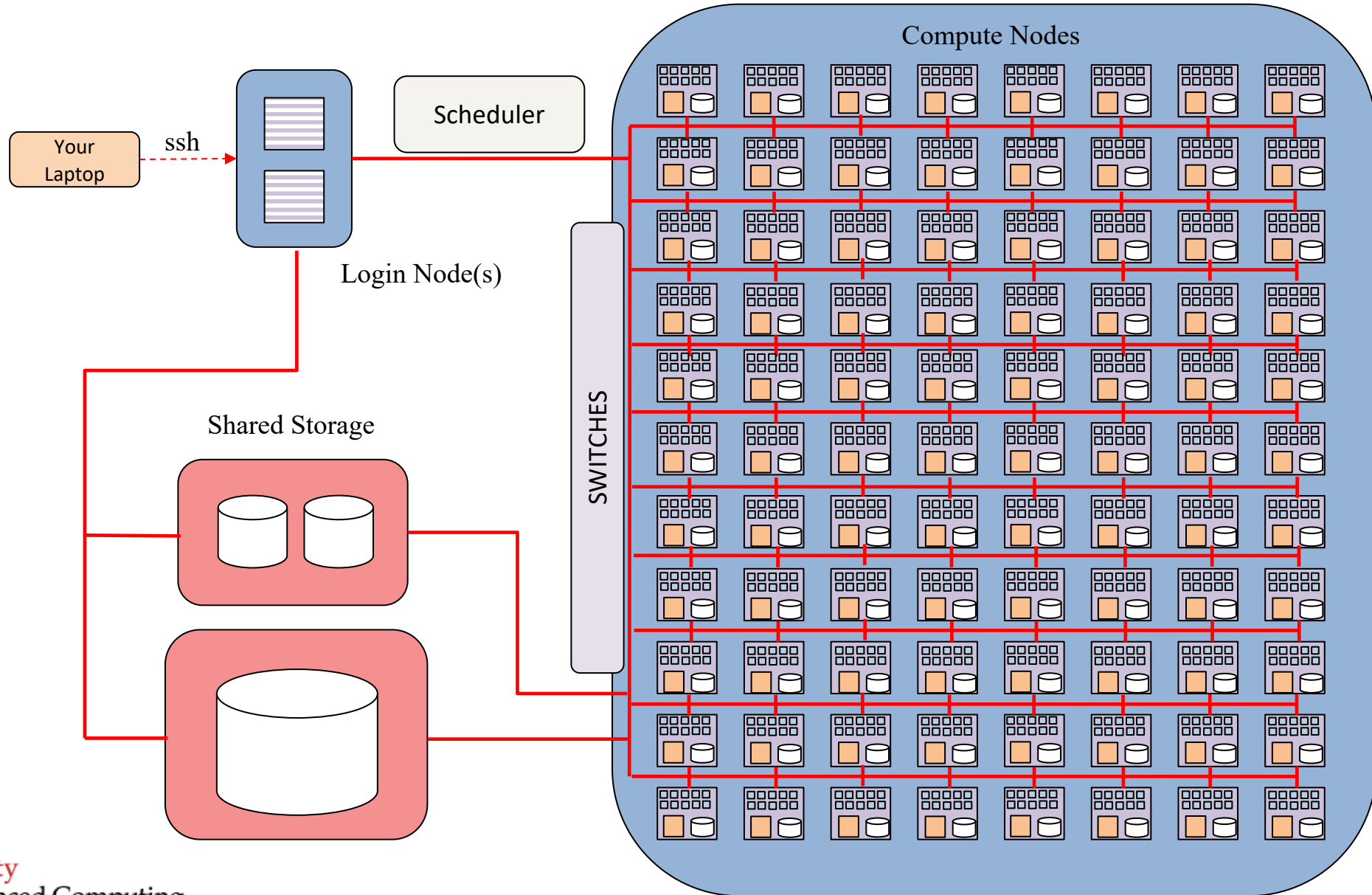
- CPUs all share memory – essentially one computer
- Expensive, likely needed for a unique purpose
  - Huge memory, huge OpenMP jobs



Princeton's Della Cluster

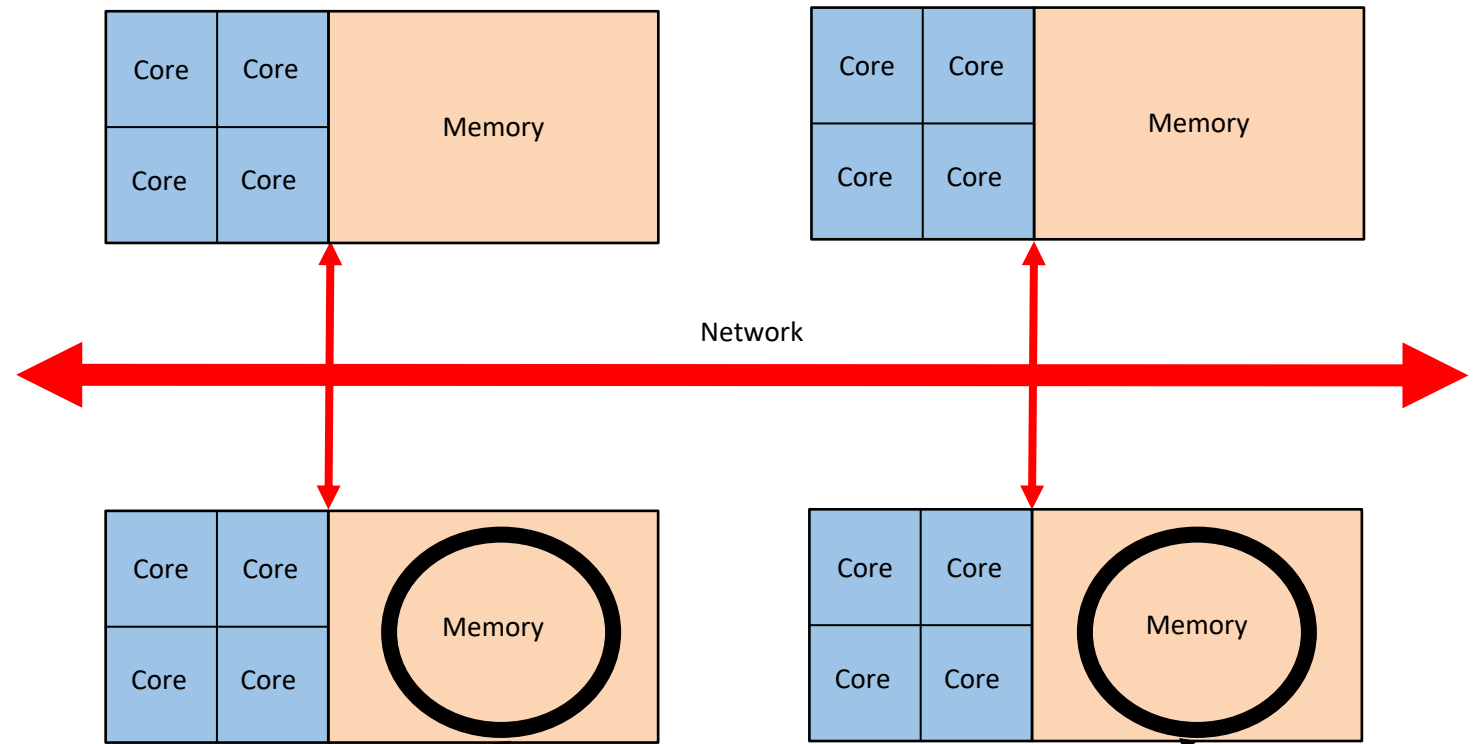


# Basic Cluster Layout



# Nodes Are Discrete Systems

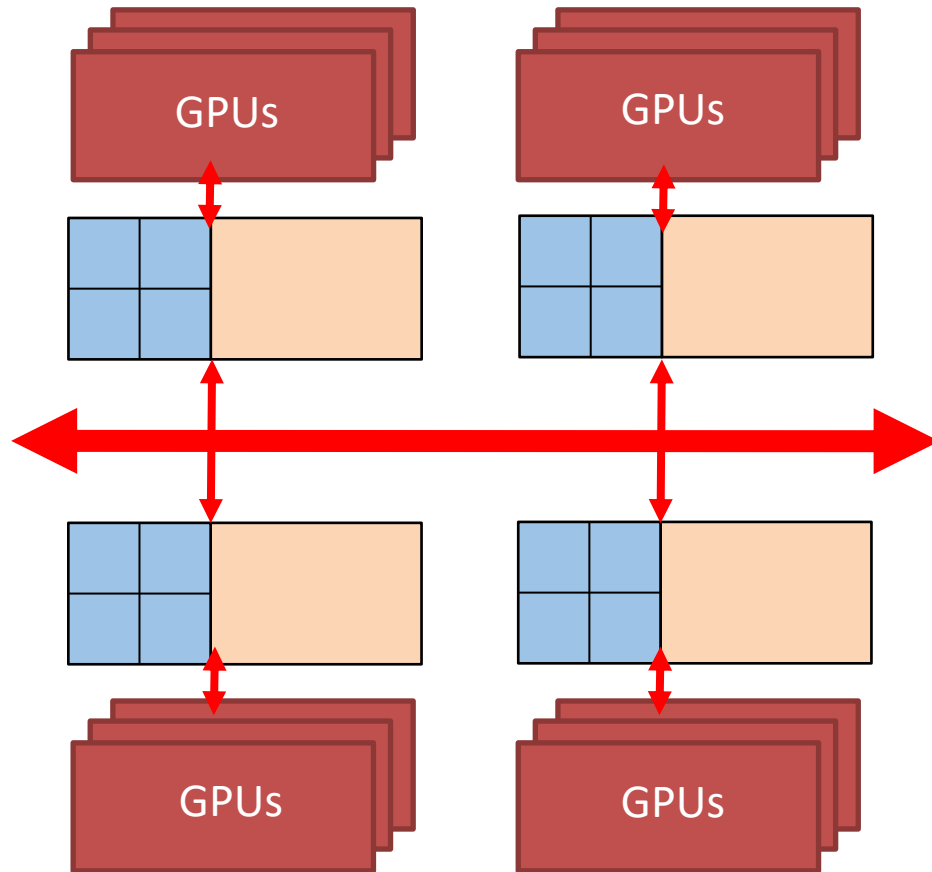
- Memory address space
  - Range of unique addresses
- Separate for each node
- Can't just access all memory in cluster



Each node has a separate address space



# Clusters With Accelerators



- “Heterogeneous” system architecture
- Accelerators: GPUs, typically
  - Or FPGAs, etc.
  - Node can have multiple accelerators
- Programmable with MPI + x
  - Where x = OpenMP, OpenACC, CUDA, ...
- Increases computational power
  - Increases FLOPS / Watt
- Trending in Top500.org
  - Strong shift toward systems with accelerators started ~10 years ago





# Outline

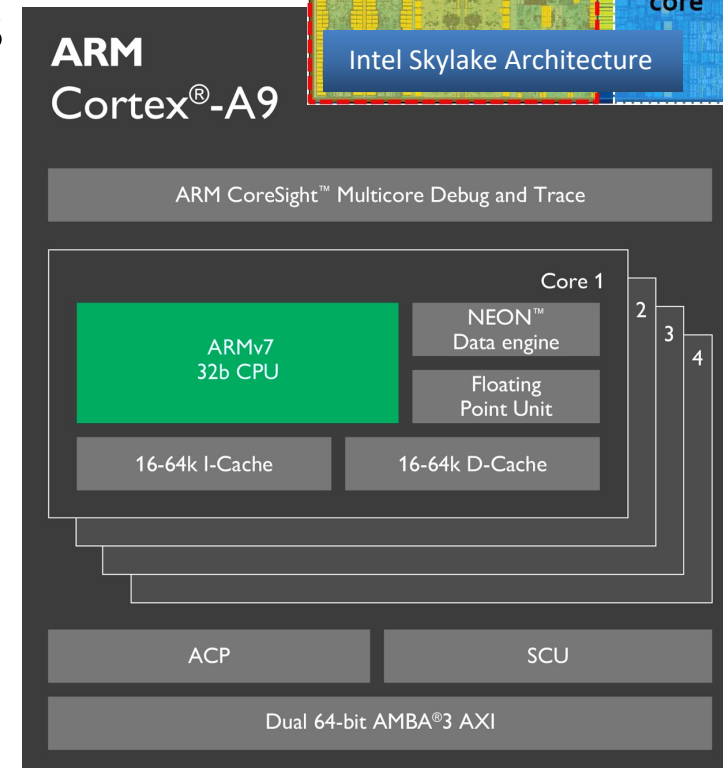
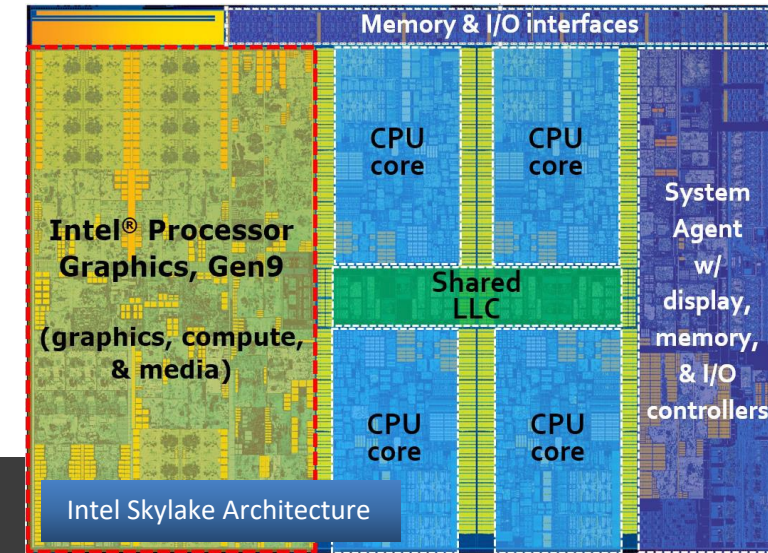
- Motivation
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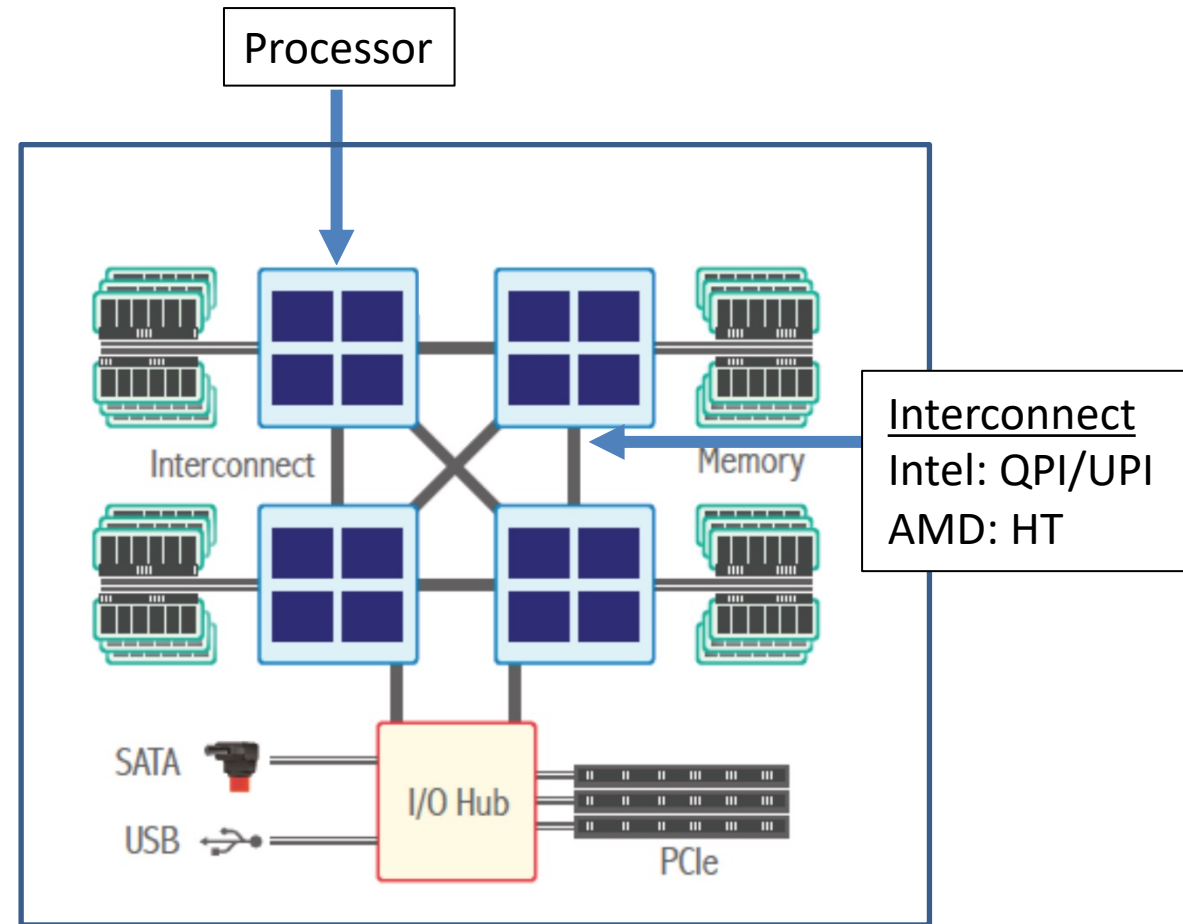
# Multicore Processors

- Nearly all modern processors are multicores
  - In servers: Intel Xeon, AMD EPYC, IBM Power
  - In laptops: Intel, AMD, ARM
  - In GPUs, phones, and mobile devices as well
- Most have vector units, multiple cache levels
- Require special care to program
  - Multi-threading, vectorization, ...
  - The free lunch is over!
- Instruction sets can vary
  - Intel and AMD: x86\_64 base, not identical
  - IBM Power, ARM, NVIDIA, etc. all differ

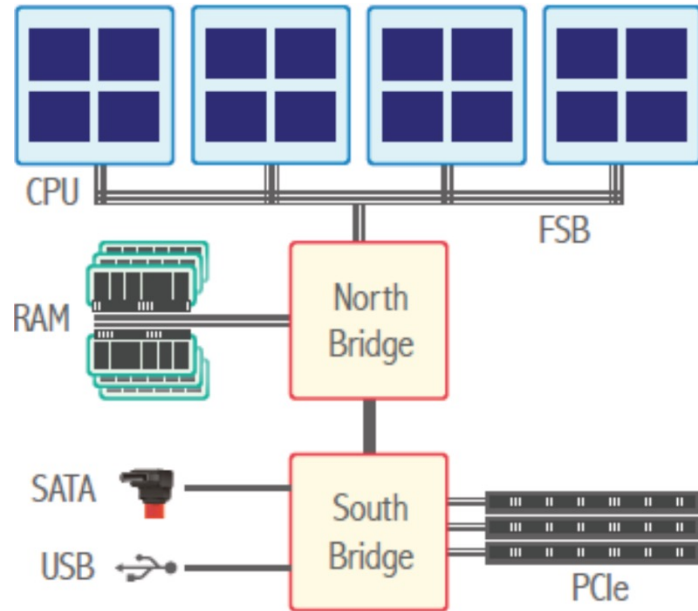


# Motherboard Layout

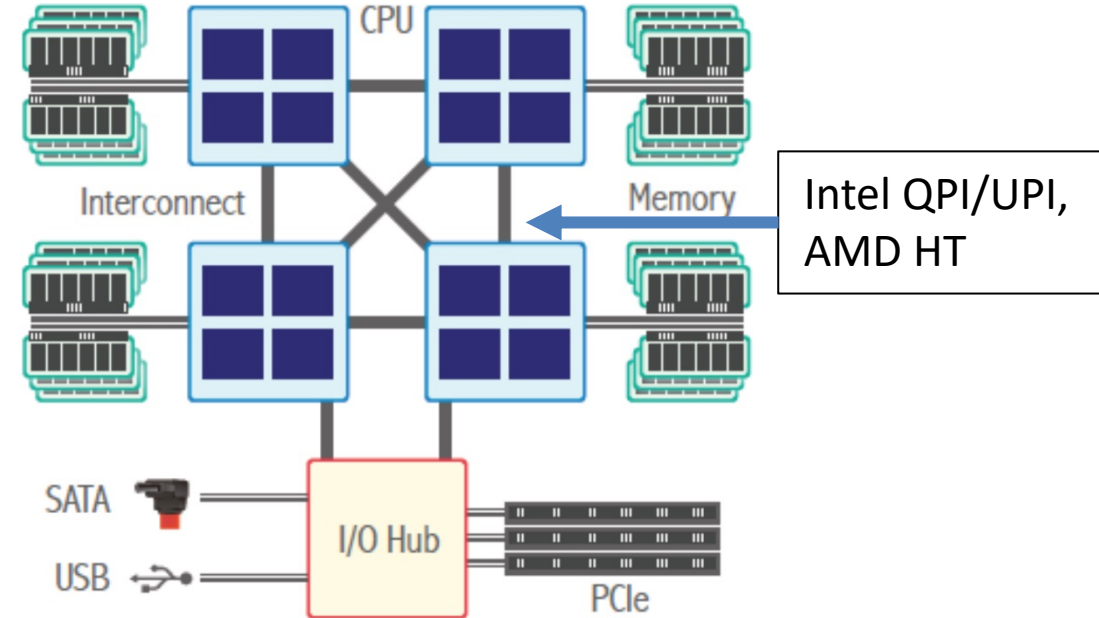
- Typical nodes have 1, 2, or 4 processors
  - 1: laptop/desktops/servers
  - 2: servers/clusters
  - 4 (or more): high end special use
- Each processor is attached to a socket
- Each processor has multiple cores
- CPU can refer to a core... or a processor
- Processors connected via interconnect
- Memory attached to processor/socket
  - Programmer sees single node memory address space



# Motherboard Layouts, Past and Present



**Symmetric MultiProcessing (SMP)** – Memory access is uniform, as all traffic goes via north bridge, but is bottlenecked by front side bus (FSB) and north-bridge-to-RAM bandwidth limitations. Current motherboards have no north bridge; the south bridge is now referred to as the I/O hub or just the chipset.

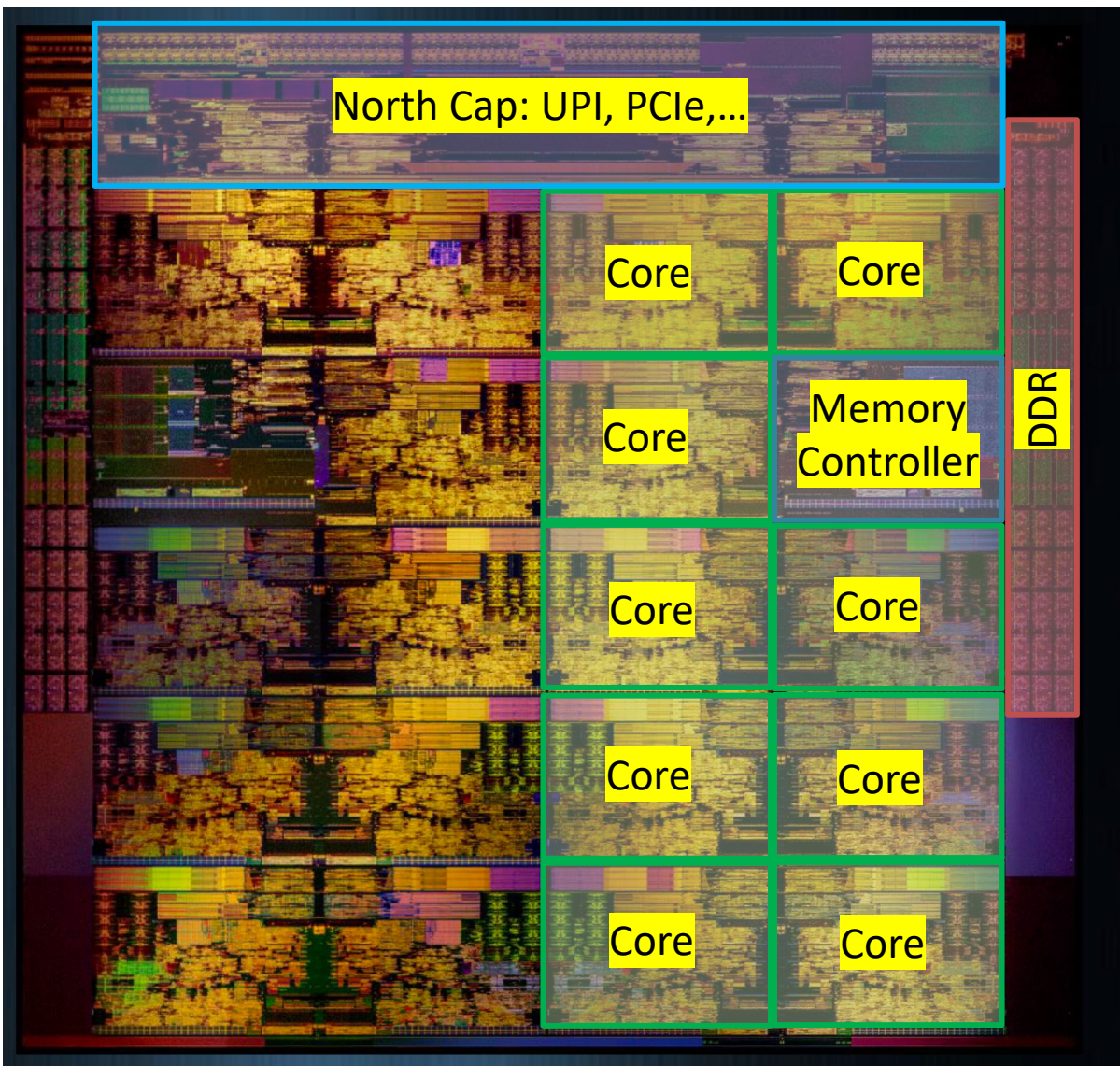


**Non-Uniform Memory Access (NUMA)** – Physical memory is partitioned per CPU, with a fast interconnect to link CPUs to each other and to I/O. This removes bottlenecks but memory is no longer uniform – there may be 30-50% extra latency to access remote memory, more in multi-hop systems.





# Example: Intel Skylake Scalable Processor

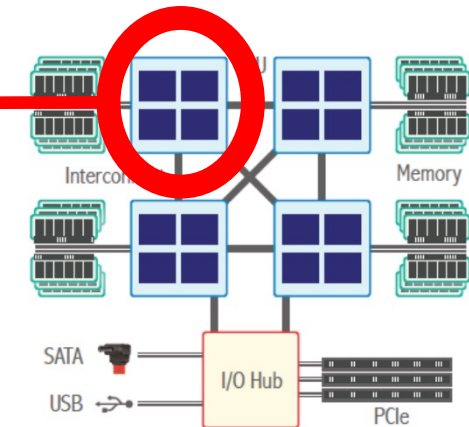


## “System on a Chip” (SoC)

- Core: “A complete ensemble of execution logic, and cache storage as well as register files plus instruction counter (IC) for executing a software process or thread.” (Jarp)

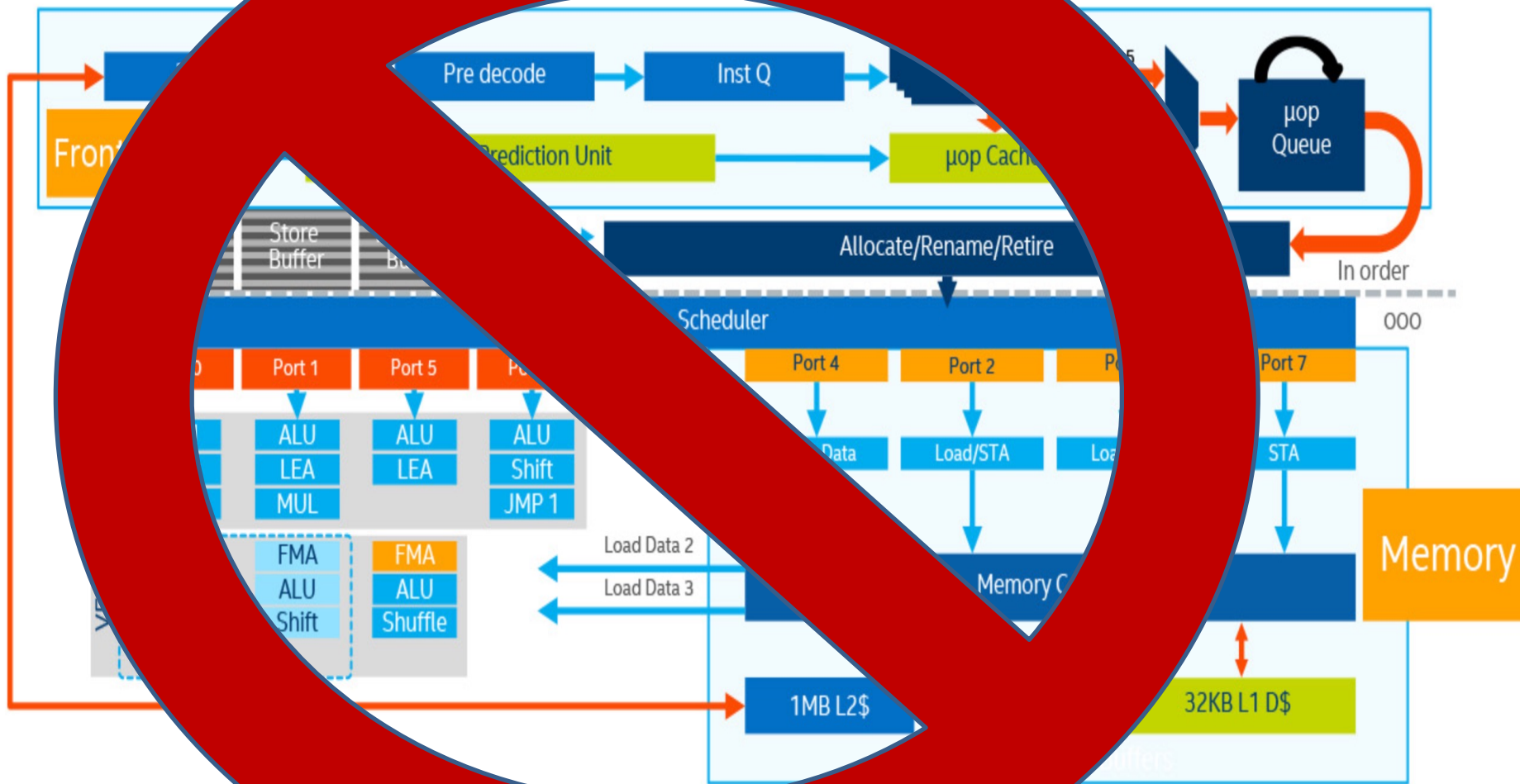


UPI – Intel Ultra Path Interconnect  
PCIe – Peripheral Component Interconnect Express  
DDR – Double Data Rate



# Skylake Core Microarchitecture

Too much!



## Key Components:

Control logic

Register file

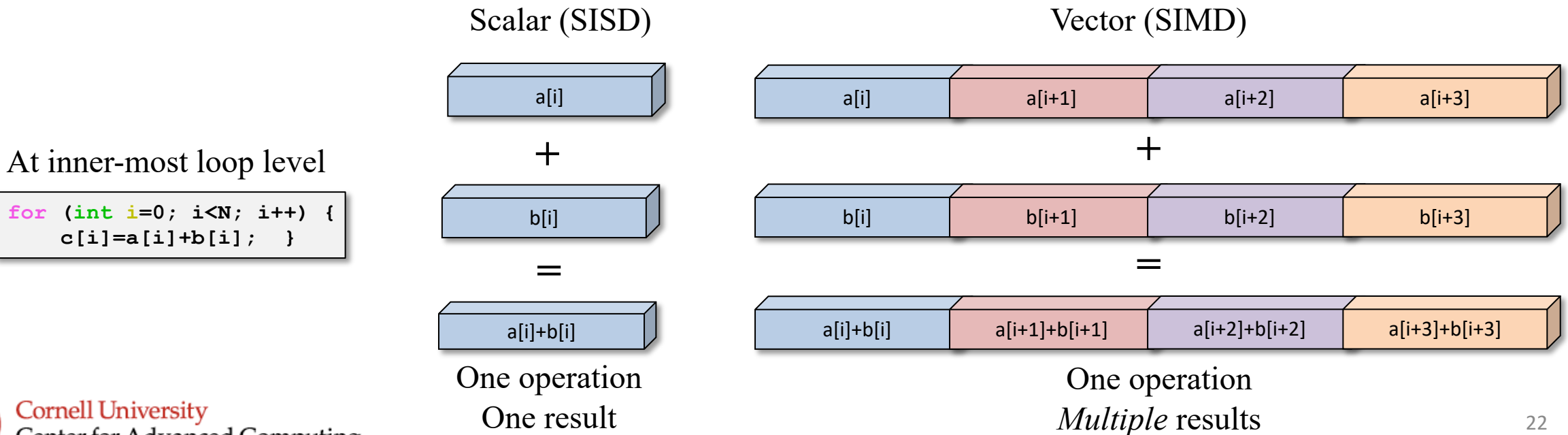
Functional Units

- ALU (arithmetic and logic unit)
- FPU (floating point unit)
- Data Transfer
- Load / Store



# Vectorization Terminology

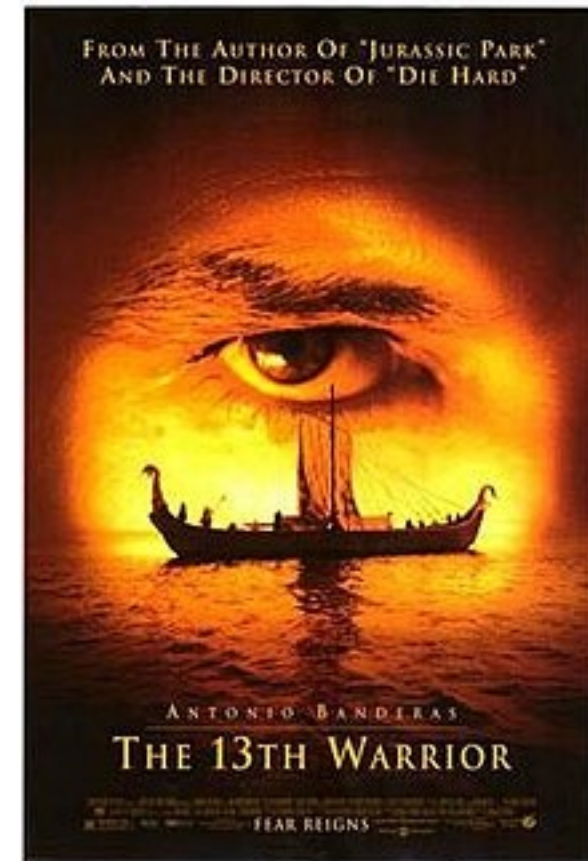
- New generations of CPUs add capabilities and instructions
  - Each core can have one or more vector processing units (VPUs) and vector registers
  - Machine (assembly) commands are often added to take advantage of new hardware
- Vector instructions are also called SIMD = Single Instruction Multiple Data
  - x86\_64 has Streaming SIMD Extensions (SSE), Advanced Vector Extensions (AVX)





# HPC Performance Metrics

- FLOP = Floating-point Operation
  - FLOPs = Floating-point Operations
  - FLOPS = Floating-point Operations Per Second
  - Often write FLOP/s or FLOP/sec to avoid ambiguity
- Calculation for single processor
  - Typically Double Precision (64-bit)
  - $\text{FLOPS} = (\text{Clock Speed}) * (\text{Cores}) * (\text{FLOPs/cycle})$
- FLOPS/\$, FLOPS/Watt are useful metrics too
- Bandwidth metrics (“giga” usually means  $10^9$ )
  - GB/s = gigabytes/sec
  - Gb/s = gigabits/sec

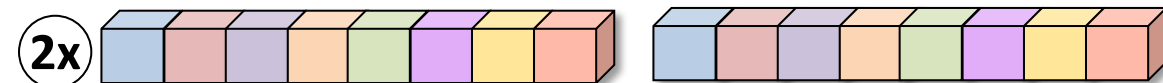
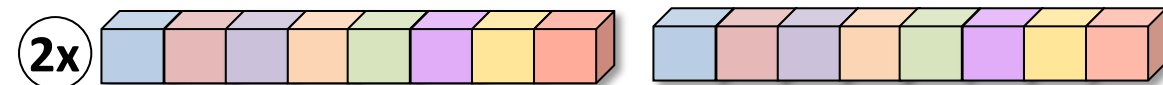
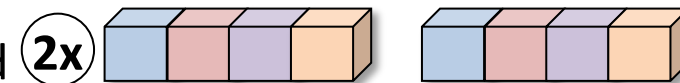
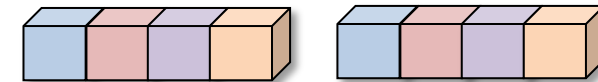
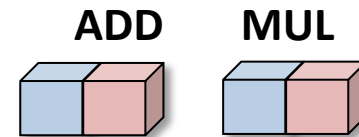


N.B. - not to be confused with a Hollywood flop!



# Intel Xeon (Server) Architecture Codenames

- Number of FLOP/s depends on width, number, and abilities of VPU's in a core
- Per-core rates, double precision (64-bit doubles – twice this for 32-bit floats)
  - Pentium 4\*... Nehalem/Westmere (SSE2... SSE4):
    - 4 DP FLOPs/cycle: 128-bit addition + 128-bit multiplication
  - Sandy Bridge/Ivy Bridge (AVX)
    - 8 DP FLOPs/cycle: 256-bit addition + 256-bit multiplication
  - Haswell/Broadwell (AVX2)
    - 16 DP FLOPs/cycle: **two**, 256-bit **FMA**, fused multiply-add (2x)
  - KNL/Skylake (AVX-512)
    - 32 DP FLOPs/cycle: **two\*\***, 512-bit **FMA**
  - Cascade Lake (AVX-512 VNNI with INT8)
    - 32 DP FLOPs/cycle: **two**, 512-bit **FMA**





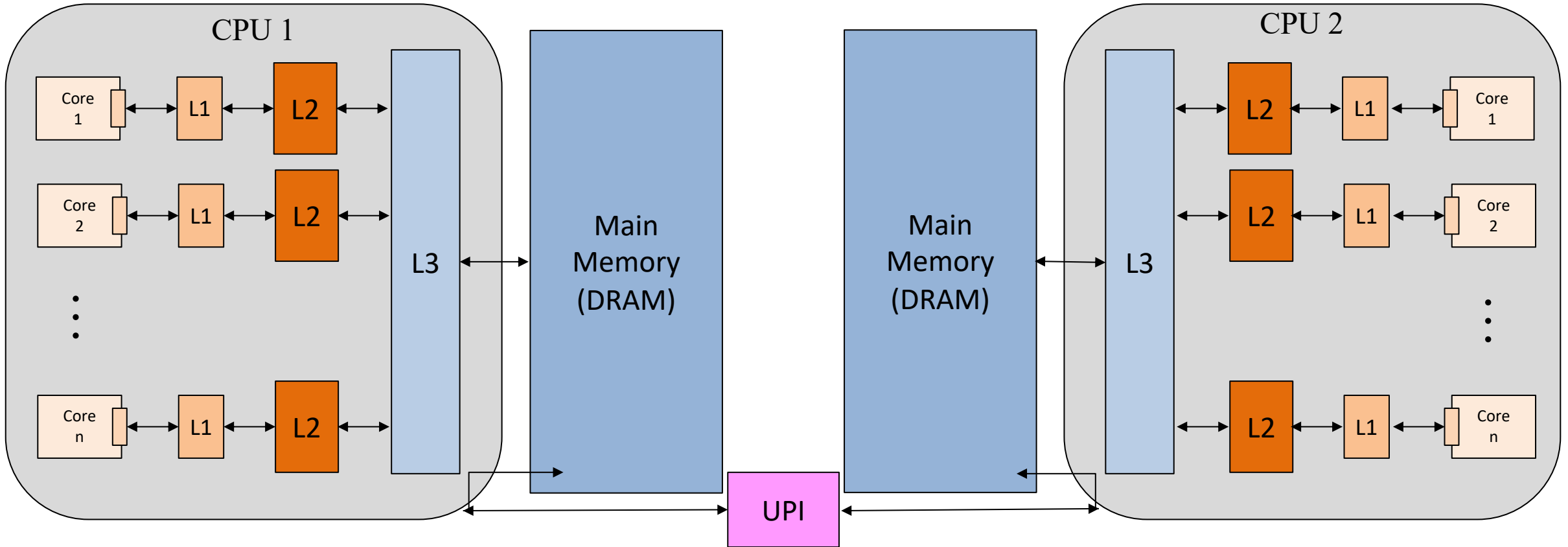
# Outline

- Motivation
- HPC Cluster
- Compute
- **Memory**
  - Layout
  - Cache
  - Performance
- **Disk**
- **Other Architectures**



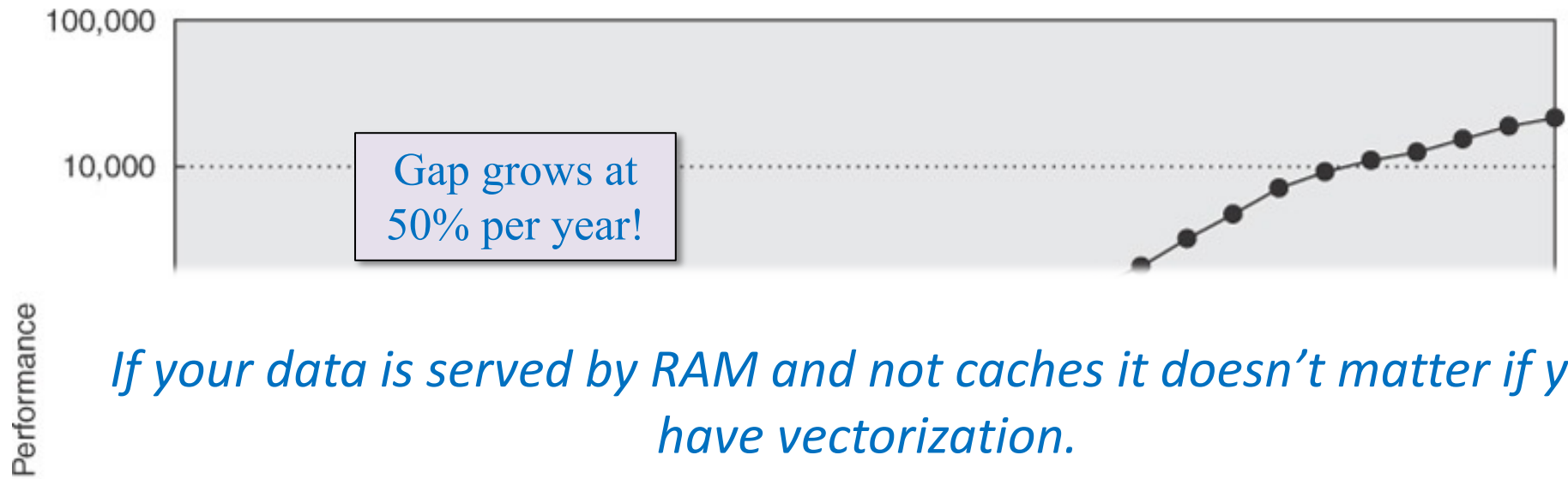
# Memory Hierarchy

Dual Socket Intel Xeon CPU

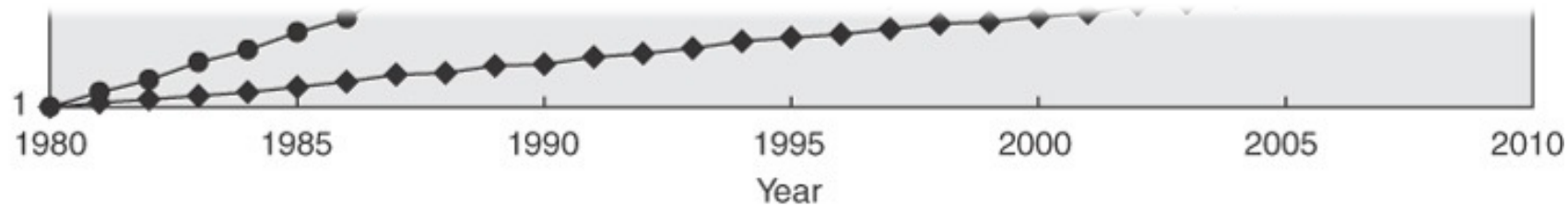


	Registers	L1 Cache	L2 Cache	L3 Cache	DRAM	Disk
Speed	1 cycle	~4 cycles	~10 cycles	~30 cycles	~200 cycles	10ms
Size	< KB per core	~32 KB per core	~256 KB per core	~35 MB per socket	~100 GB per socket	TB

# Growth in Memory Performance Lags CPU



*To increase performance, try to minimize memory footprint.*



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# Outline

- Motivation
- HPC Cluster
- Compute
- Memory
- **Disk**
  - Types
  - Filesystems
- **Other Architectures**



# File I/O

“A supercomputer is a device for turning compute-bound problems into I/O-bound problems.”

*-- Ken Batcher, Emeritus Professor of Computer Science at Kent State University*



# Types of Disk

- Hard Disk Drive (HDD)
  - Traditional Spinning Disk
- Solid State Drives (SSD)
  - ~5x faster than HDD
- Non-Volatile Memory Express (NVMe)
  - ~5x faster than SSD

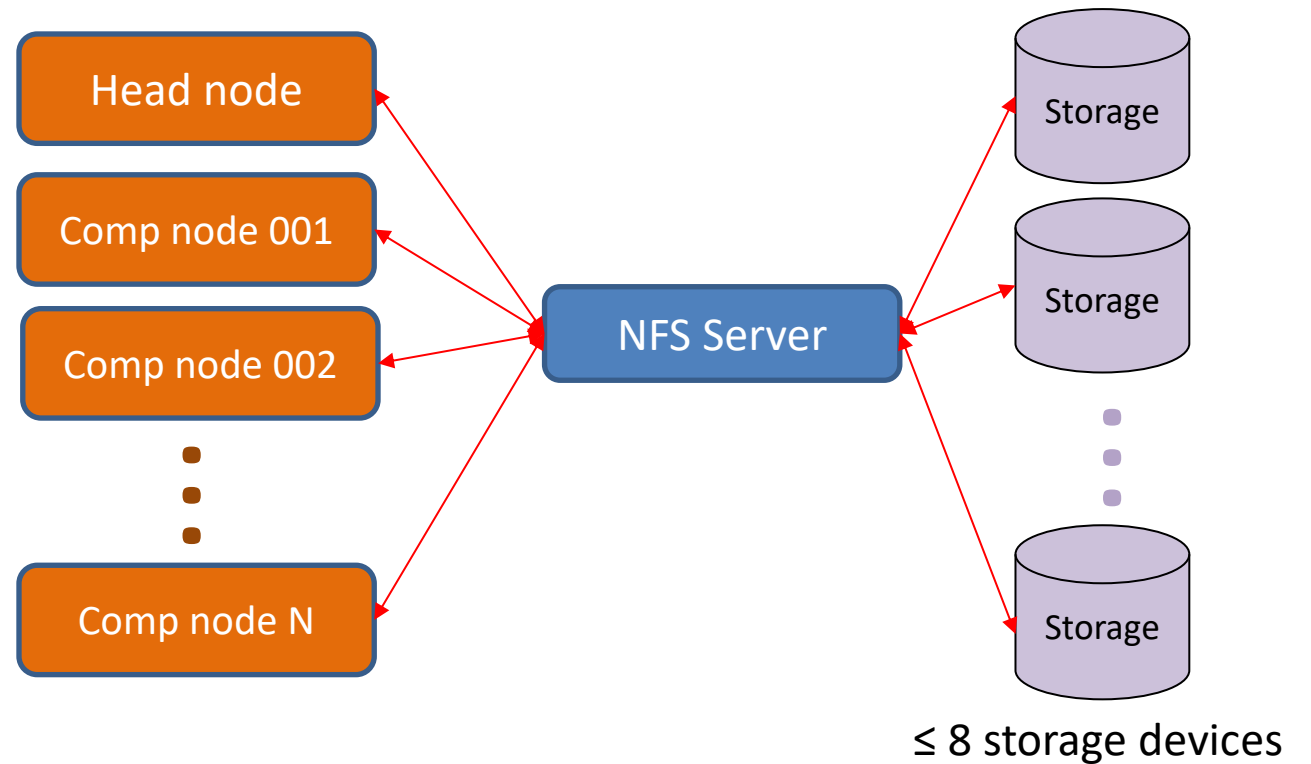


Photo Credit: Maximum PC



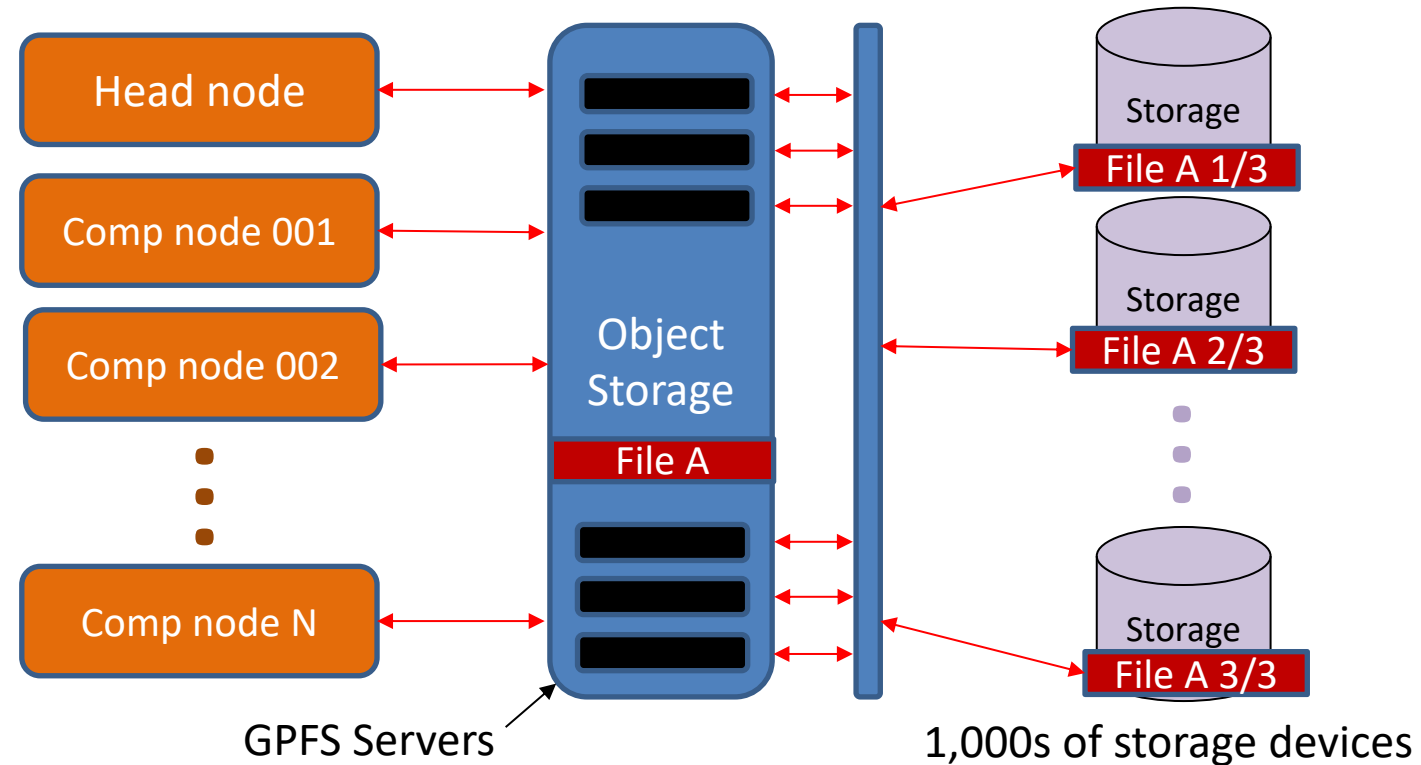
# Types of Filesystems - NFS

- NFS – Network File System
  - Simple, cheap, and common
  - Single filesystem across network
  - Not well suited for large throughput



# Parallel Filesystems

- GPFS (General Parallel Filesystem – IBM)
  - Designed for parallel read/writes
  - Large files spread over multiple storage devices
  - Allows concurrent access
  - Significantly increase throughput
- Lustre
  - Similar idea
  - Different implementation
- Parallel I/O library in software
  - Necessary for performance realization





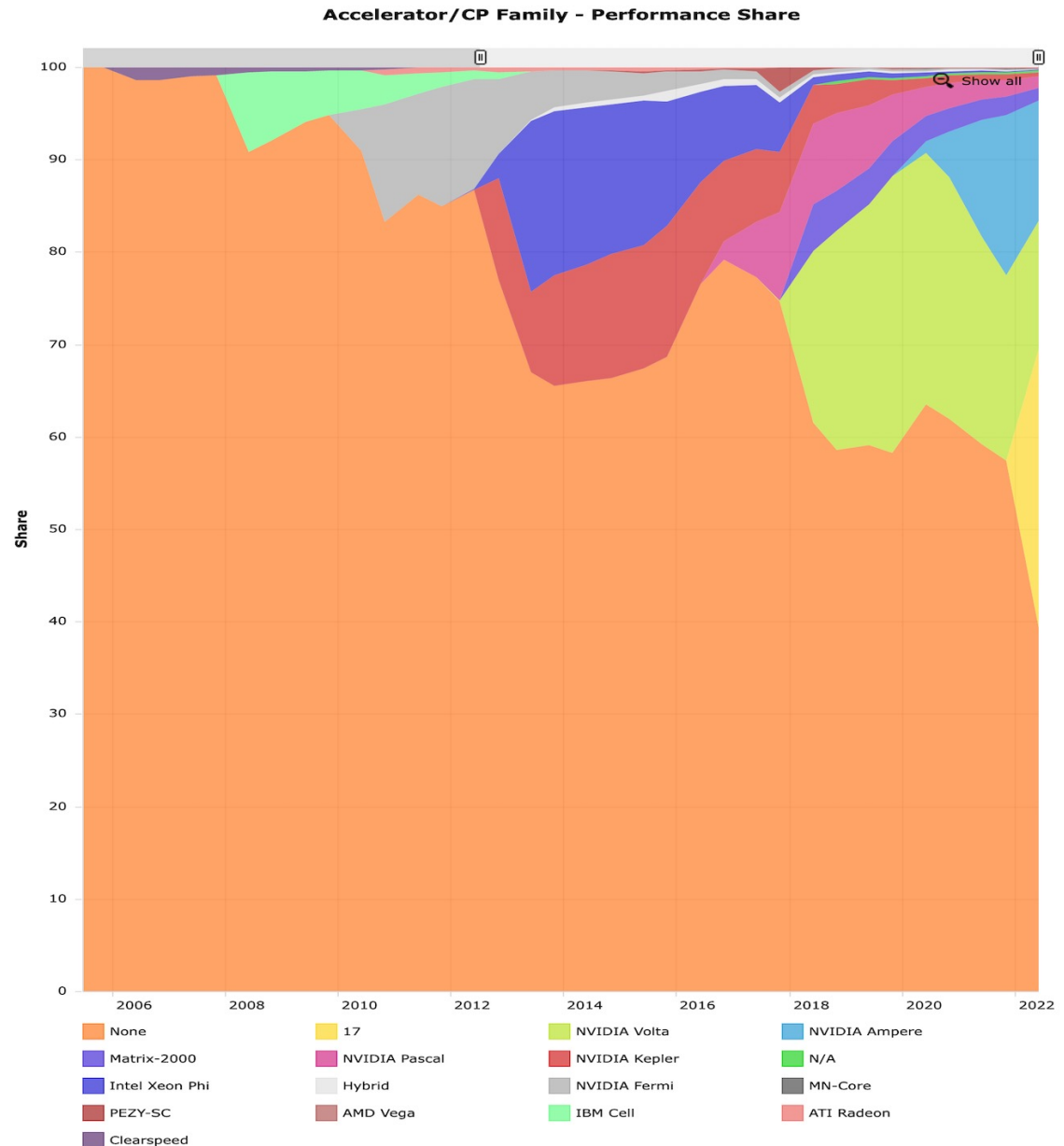
# Outline

- Motivation
- HPC Cluster
- Compute
- Memory
- Disk
- Other Architectures
  - GPUs
  - Xeon Phi
  - Cloud

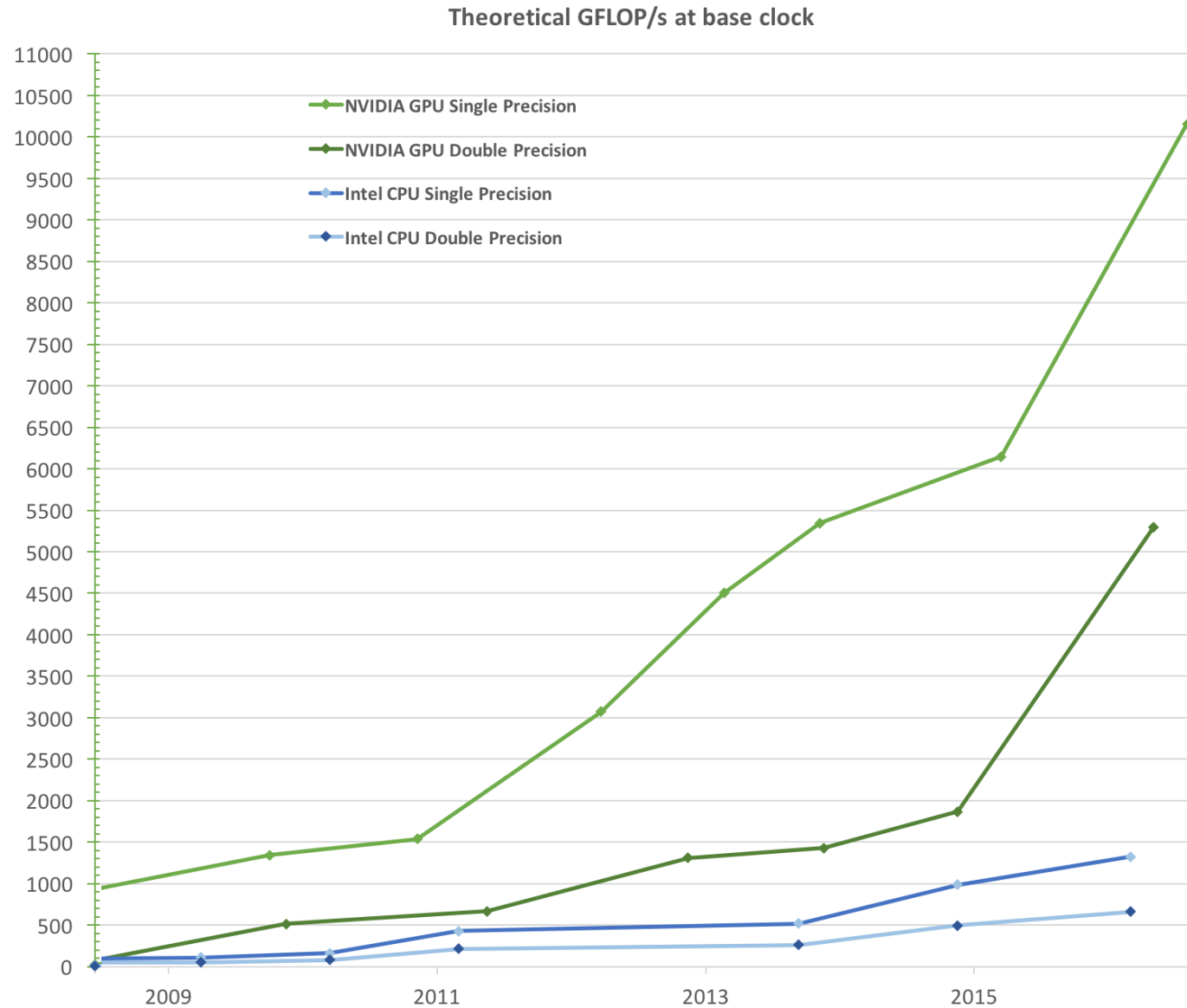


# Heterogeneous Systems on the Rise

- The computing landscape changes rapidly
- 60% of TOP500 systems now have accelerators (June 2022)
- Graphics processing units (GPUs) are by far the most common type of accelerator



# GPU and CPU Performance Trends



# General Purpose GPUs

- General Purpose GPU (GPGPU)
  - NVIDIA Pascal/Volta/Ampere...
  - AMD Radeon Instinct, others
- Always attached to a CPU host
  - Data travels to device over PCIe
  - NVIDIA NVLink has higher speed
- Not compatible with x86
- Programmable sort-of-like CPUs
  - NVIDIA CUDA: extensions to C++
  - OpenCL, OpenACC, OpenMP, ...
  - Need compatible compiler, libraries

NVIDIA Volta V100



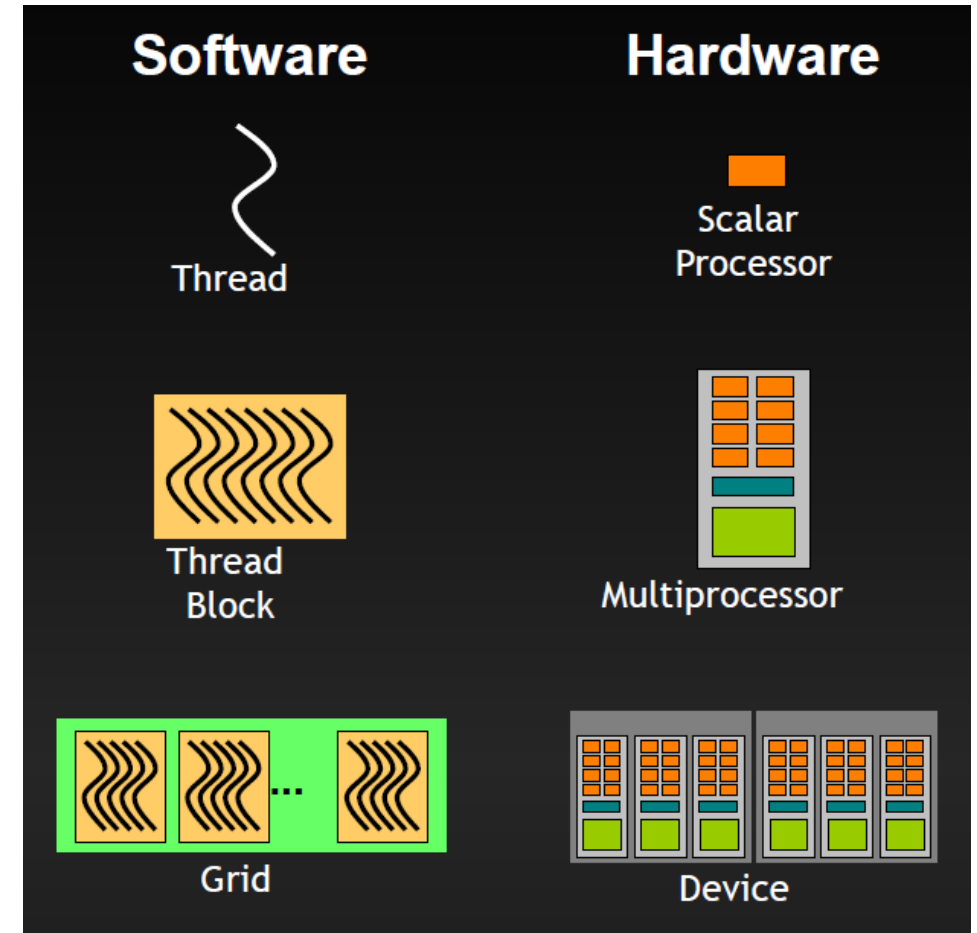
# NVIDIA Tesla V100 (V for “Volta”)

- 80 Streaming Multiprocessors (SMs)
  - Analogous to CPU cores
  - Execute *only* SIMD-type instructions
- One SM holds many “CUDA cores”
  - Analogous to vector lanes
  - 64 FP32 CUDA cores
  - 64 INT32 CUDA cores
  - 32 FP64 CUDA cores
- One SM also has 8 tensor cores
  - Fast 4x4 matrix multiplications in FP16
- Device memory: 32 GB of HBM2



# NVIDIA Execution Model

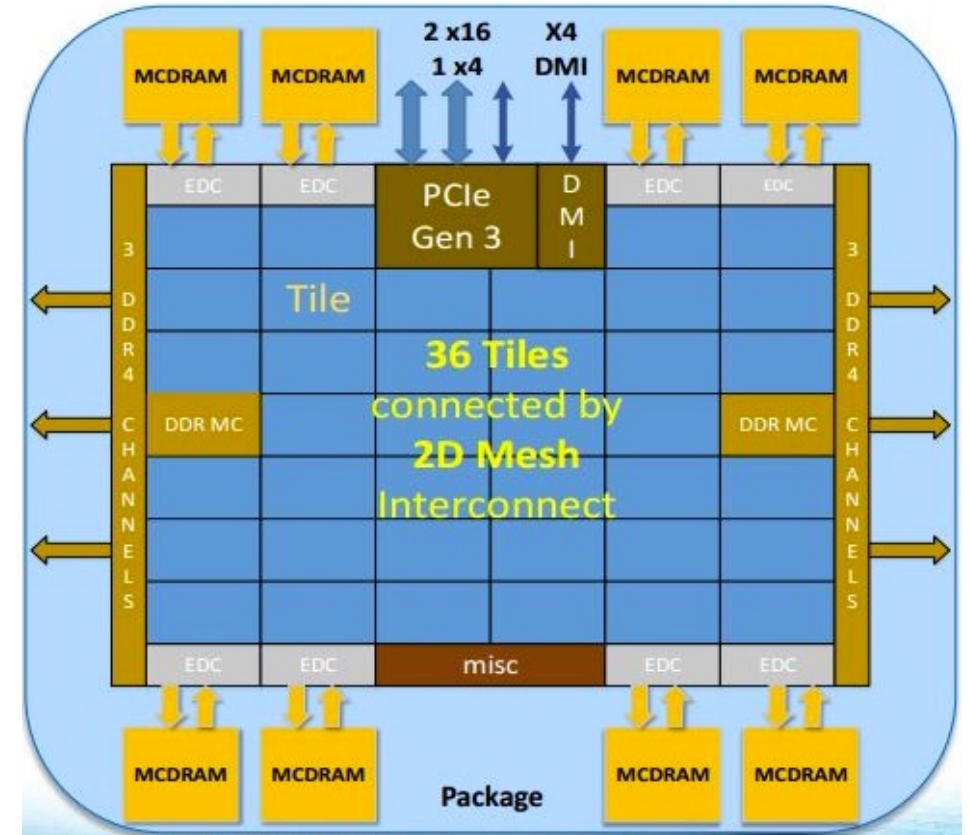
- SIMT = Single Instruction Multiple Thread
  - Operations apply to “warps” of 32 threads
  - A warp of threads is like a CPU vector
  - Not all that different from SIMD
- CUDA core = scalar (thread) processor
  - Instructions only go to groups of 32
  - A thread block must be split into warps of 32
  - Thus, an SM is like 1 or 2 vector units in a CPU
- One thread block maps to one SM
- A grid of thread blocks can be spread over the entire device





# R.I.P. Intel Xeon Phi, a.k.a. Intel MIC

- MIC: Many Integrated Cores
  - x86-compatible multiprocessor architecture
- Programmable just CPUs
  - MPI, OpenMP, OpenCL, ...
  - Same compilers as CPUs
- But many cores, fast MCDRAM like GPUs
  - Intel's "answer" to the GPU challenge
- Started out as a coprocessor
  - Data travels over PCIe
  - Became main processor in 2nd generation
- Eventually merged into Xeon line



# Processors vs. PCIe Devices, Circa 2019



	Xeon Gold 5122 (2017)	Xeon Platinum 8280M (2019)	Xeon Phi 7290F (2017)	NVIDIA V100 (2017)
Cores	4	28	72	84 SMs
Logical Cores	8	56	288	5120 cores
Clock rate	3.6 – 3.7 GHz	2.5 – 3.8 GHz	1.5-1.7 GHz	1530 MHz
Theoretical GFLOPS (double)	460.8	2240	3456	7450
SIMD width	512 bit	512 bit	512 bit	Warp of 32 threads
Memory	--	--	16 GB MCDRAM 384 GB DDR4	32 GB
Memory B/W	127.8 GB/s	127.8 GB/s	400+ GB/s MCDRAM 115.2 GB/s RAM	900 GB/s
Approx. Unit Price	\$1,200	\$12,000	\$3,400	\$9,000





# Demystifying the Cloud

- “Regular” computers, just somewhere else
- Provide users with remote virtual machines or containers
- Can be used for anything:
  - Mobile services, website hosting, business applications, ...
  - **Data analysis, high performance computing**
- Providers
  - Amazon Web Services (AWS)
  - Microsoft Azure
  - Google Cloud Platform (GCP)
  - Oracle Cloud
  - Lots of others



# Cloud Computing Pros and Cons

- Advantages:
  - Potentially lower cost
    - Pay as you go
    - Save on sysadmins and infrastructure
    - Economy of scale
  - Scaling up or down as needed
    - Can be used to run overflow from a regular data center
  - Access to a wide range of hardware
- Challenges:
  - Data movement
    - Expensive and time consuming
  - Security, privacy, ...



# What We Didn't Talk About

- Microarchitecture details (ALU, FPU, pipelining...)
- Memory bandwidth and latency
- Cache lines and cache coherence
- IBM (Power) or AMD processors
- FPGAs, Google TPUs, NPUs, ...



# Resources & References

- Very nice glossary: <https://cvw.cac.cornell.edu/main/glossary>
- J. Hennessy, D. Patterson, Computer Architecture: A Quantitative Approach, 6th edition (2017), ISBN 978-0128119051
- U. Drepper, What Every Programmer Should Know About Memory, <http://people.redhat.com/drepper/cpumemory.pdf>
- NVIDIA Volta Architecture Whitepaper <https://images.nvidia.com/content/volta-architecture/pdf/volta-architecture-whitepaper.pdf>

